MD5 Series

5-Phase Stepper Motor Driver

Small, light and high speed and torque 5-phase stepper motor driver

- Bipolar constant pentagon drive method
- Includes Auto Current Down and self-diagnosis function
- Low speed rotation and high accuracy controlling with microstep-driving (Except for MD5-ND14)

[Max. resolution - 250 division / In case of 5-phase stepper motor of which basic step angle is 0.72°, it enables to control up to 0.00288° per pulse and it requires 125,000 pulses per rotation.]

- Photocoupler input insulation method to minimize the effects from external noise

⚠️ Please read “Caution for your safety” in operation manual before using.

■ Ordering information

<table>
<thead>
<tr>
<th>MD</th>
<th>5</th>
<th>H</th>
<th>F</th>
<th>14</th>
<th>-</th>
</tr>
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<tbody>
<tr>
<td>Output</td>
<td>No mark</td>
<td>Zero point excitation output</td>
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<tr>
<td>AO</td>
<td>Alarm output</td>
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<tr>
<td>14</td>
<td>1.4A/Phase</td>
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<td>28</td>
<td>2.8A/Phase</td>
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<tr>
<td>Power supply</td>
<td>D</td>
<td>20-35VDC</td>
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<tr>
<td>F</td>
<td>100-220VAC</td>
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<tr>
<td>Step type (Resolution)</td>
<td>H</td>
<td>Micro step(250divisions)</td>
<td></td>
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<tr>
<td>Motor phase</td>
<td>N</td>
<td>Normal Step</td>
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<tr>
<td>5</td>
<td>5-Phase</td>
<td></td>
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<tr>
<td>MD</td>
<td>Motor Driver</td>
<td></td>
<td></td>
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<td></td>
</tr>
</tbody>
</table>

※1: Except MD-5ND14

■ Specifications

<table>
<thead>
<tr>
<th>Model</th>
<th>MD5-HD14</th>
<th>MD5-HF14</th>
<th>MD5-HF14-AO</th>
<th>MD5-HF28</th>
<th>MD5-ND14</th>
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<tbody>
<tr>
<td>Power supply</td>
<td>20-35VDC 3A*1</td>
<td>100-220VAC 50/60Hz</td>
<td>20-35VDC 3A*1</td>
<td></td>
<td></td>
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<tr>
<td>RUN current</td>
<td>0.4 to 1.4A / Phase</td>
<td>1.0 to 2.8A / Phase</td>
<td>0.5 to 1.5A / Phase</td>
<td></td>
<td></td>
</tr>
<tr>
<td>RUN method</td>
<td>Bipolar constant pentagon drive</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Basic step angle</td>
<td>0.72° / Phase</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Resolution</td>
<td>1, 2, 4, 5, 8, 10, 16, 20, 25, 40, 50, 80, 100, 125, 200, 250 division (0.72° to 0.00288° / Phase)</td>
<td></td>
<td></td>
<td></td>
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</tr>
<tr>
<td>Input pulse width</td>
<td>Min. 0.5μs</td>
<td>0.1μs</td>
<td>Min. 10μs</td>
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<tr>
<td>Pulse Duty</td>
<td>50%</td>
<td></td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>Rising/Falling time</td>
<td>Max. 120ns</td>
<td>Max. 1μs</td>
<td>Max. 120ns</td>
<td></td>
<td></td>
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<td>1MHz</td>
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<td>Input voltage level</td>
<td>500kHz</td>
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<td></td>
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<td>50kHz</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input resistance</td>
<td>High : 4-8VDC, Low : 0-0.5VDC</td>
<td></td>
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<tr>
<td>Ambient temperature</td>
<td>0 to 40°C, storage : -20 to 60°C</td>
<td></td>
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<td></td>
</tr>
<tr>
<td>Ambient humidity</td>
<td>35 to 85%RH, storage : -10 to 90%RH</td>
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<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Approval</td>
<td>C</td>
<td>C</td>
<td>C</td>
<td>C</td>
<td>C</td>
</tr>
<tr>
<td>Unit weight</td>
<td>Approx. 220g</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Approx. 660g</td>
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<tr>
<td>Approx. 650g</td>
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<td></td>
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</tr>
<tr>
<td>Approx. 1kg</td>
<td></td>
<td></td>
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<td></td>
</tr>
<tr>
<td>Approx. 120g</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

※1: When using over 30VDC, it should be mounted at ventilated place due to increasing heat.
※2: Max. pull-out frequency and max. slewing frequency are variable depending on resolution, or load.
※Environment resistance is rated at no freezing of condensation.
**MD5 Series**

5-Phase micro stepper motor driver [MD5-HD14]

### Function selection switch

<table>
<thead>
<tr>
<th>NO</th>
<th>Name</th>
<th>Function</th>
<th>Switch position</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>TEST</td>
<td>Self-diagnosis</td>
<td>ON</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Rotate in 30rpm</td>
<td>OFF</td>
</tr>
<tr>
<td>2</td>
<td>1/2 CLK</td>
<td>Pulse input method</td>
<td>1 Pulse input</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>2 Pulse input</td>
</tr>
<tr>
<td>3</td>
<td>C/D</td>
<td>Auto current down</td>
<td>Not using</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Using</td>
</tr>
</tbody>
</table>

**TEST**
- Self-diagnosis function is to test motors and drivers.
- Motors rotate with 30 rpm in full-step. Motor rotation speed is subject to change depending on resolution setting.
- Rotation speed = 30 rpm / resolution
- The motor will rotate in CCW direction when in 1-pulse input mode and in CW direction when in 2-pulse input mode.
- Note) Make sure that TEST switch is set to OFF before supplying the power. It may cause injury or danger if TEST switch is set to ON when power is supplied.

**1/2 CLK**
- 1/2 CLK switch is to select pulse input mode.
- 1-pulse input mode: CW → operation command pulse input, CCW → rotation direction pulse input
  - [H]: CW rotation, [L]: CCW rotation
- 2 Puls input mode: CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input

**C/D (Auto current down)**
- This function is reducing current automatically according to STOP current setting value in order to suppress generated heat when motor is stop.
- It activates when there is no pulse input of motor operation for over 200ms.

**RUN current setting**

<table>
<thead>
<tr>
<th>S/W No</th>
<th>Current (A/Phase)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0.4</td>
</tr>
<tr>
<td>1</td>
<td>0.5</td>
</tr>
<tr>
<td>2</td>
<td>0.57</td>
</tr>
<tr>
<td>3</td>
<td>0.63</td>
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<td>4</td>
<td>0.71</td>
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<tr>
<td>5</td>
<td>0.77</td>
</tr>
<tr>
<td>6</td>
<td>0.84</td>
</tr>
<tr>
<td>7</td>
<td>0.9</td>
</tr>
<tr>
<td>8</td>
<td>0.96</td>
</tr>
<tr>
<td>9</td>
<td>1.02</td>
</tr>
<tr>
<td>A</td>
<td>1.09</td>
</tr>
<tr>
<td>B</td>
<td>1.15</td>
</tr>
<tr>
<td>C</td>
<td>1.22</td>
</tr>
<tr>
<td>D</td>
<td>1.22</td>
</tr>
<tr>
<td>E</td>
<td>1.33</td>
</tr>
<tr>
<td>F</td>
<td>1.4</td>
</tr>
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</table>

**STOP current setting**

<table>
<thead>
<tr>
<th>Switch No.</th>
<th>%</th>
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<tbody>
<tr>
<td>0</td>
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<td>1</td>
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<td>2</td>
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<td>B</td>
<td>74</td>
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<td>C</td>
<td>78</td>
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<td>D</td>
<td>82</td>
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<tr>
<td>E</td>
<td>86</td>
</tr>
<tr>
<td>F</td>
<td>90</td>
</tr>
</tbody>
</table>

**RUN current is a phase current provided to 5-phase stepper motor.**
- Be sure to set RUN current at the rated current or below.
- Adjust the RUN current in case severe heat generation occurs. Be sure that torque decreasing may occur when adjusting the current.
- Note) Be sure to adjust RUN current while motor is running.

**STOP current setting**
- STOP current is a phase current provided to 5-phase stepper motor at standstill.
- It will be activated when C/D (Auto current down) is set to ON. By setting STOP current, it is possible to suppress the heat generation at motor standstill.
- STOP current setting value is the ratio of RUN current setting value (%).
- Ex) In case RUN current setting value is set to 1.4A and STOP current setting value is set to 50%, auto current down current is set to 0.7A.
- STOP current setting value may have some deviation depending on resistance impedance of motor.
- Auto current down function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.
- Note) Be sure to adjust STOP current while motor is at standstill.
© Zero point excitation output signal (ZERO OUT)

※ The signal is output to indicate when the motor excitation status is in the initial stage. Used to check the rotation position of motor's axis.
※ In case of full step, the signal is output every 7.2°. (50 times / rotation).
Ex) Full step (0.72°/Step) : Signal is output every 10 pulses
  20 divisions (0.036°/Step) : Signal is output every 200 pulses.

© HOLD OFF function
※ When HOLD OFF input signal is [H], motor excitation is released.
  When HOLD OFF input signal is [L], motor excitation is in a normal status.
※ A function used to rotate motor's axis using external force or used for manual positioning.
※ HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.
※ Please do not use for stopping motor.

© Setting microstep(Microstep : Resolution)

- Resolution setting(Same as MS1, MS2)
  ※ It is set to MS1 when division selection signal is [L], and MS2 when division selection signal is [H].
  ※ Two different micro step can be set using DIVISION SELECTION. Users can select one of them via external input signals.
  ※ Microstep is to make basic step angle of 5-phase motors (0.72°) divided into smaller angle according to setting values.
  ※ The formula for microstep is angle ;
  Motor revolution angle (5-phase motors) = \[\frac{\text{Basic step angle(0.72°)}}{\text{Resolution}}\]
  ※ In case of geared motors, step angle shall be determined by dividing step angle by gear ratio.
  EX) 0.72°/10 (1:10) = 0.072°
  ※ It may cause step-out if resolution is changed while motor is running.

■ Input-Output diagram

※ CW
  2-pulse input mode - CW direction rotation pulse input
  1-pulse input mode - Operation command pulse input

※ CCW
  2-pulse input mode - CCW direction rotation pulse input
  1-pulse input mode - Rotation direction pulse input
  [H] : CW, [L] : CCW

※ HOLD OFF
  Motor excitation OFF control signal
  [H] : Motor excitation OFF

※ DIVISION SELECTION
  Division selection signal
  → [L] : Operated by MS1 setting resolution.
  → [H] : Operated by MS2 setting resolution.

※ ZERO OUT
  Zero point excitation output signal ON for zero point excitation
Connections

- CW+
- CW-
- CCW+
- CCW-
- HOLD OFF+
- HOLD OFF-

User Controller

Division selection + signal
Zero point excitation output signal

Power 20-35VDC

Motor

Note: Add external resistance when power for pulse from the external of the unit exceeds +5V.
(Input current: 10 to 20mA)

※Please refer to Q-37 for standard wiring.

Dimensions

(unit: mm)

- 4.5 x 4.5 x 100 x 94 x 100 x 105
- 20 x 39.5 x 74 x 76.5
**5-Phase Micro stepper motor driver [MD5-HF14]**

- **TEST**
  - Self-diagnosis function is to test motors and drivers.
  - Motors rotate with 250Hz in full-step. Motor rotation speed is subject to change depending on resolution setting.
  - Rotation speed = 30 rpm / resolution
  - The motor will rotate in CCW direction when in 1-pulse input mode and in CW direction when in 2-pulse input mode.
  - Make sure that TEST switch is set to OFF before supplying the power.
  - It may cause injury or danger if TEST switch is set to ON when power is supplied.

- **2/1 CLK**
  - 1/2 CLK switch is to select pulse input mode.
  - 1-pulse input mode: CW → operation command pulse input, CCW → rotation direction pulse input
    - ([H]: CW rotation, [L]: CCW rotation)
  - 2-Pulse input mode: CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input

- **C/D (Auto current down)**
  - This function is reducing current automatically according to STOP current setting value in order to suppress generated heat when motor is stop.
  - It activates when there is no pulse input of motor operation for over 200ms.

- **STOP current setting**
  - It will be activated when C/D (Auto current down) is set to ON. By setting STOP current, it is possible to suppress the heat generation at motor standstill.
  - STOP current setting value is the ratio of RUN current setting value (%).
  - Ex) In case RUN current setting value is set to 1.4A and STOP current setting value is set to 50%, auto current down current is set to 0.7A.
  - STOP current setting value may have some deviation depending on resistance impedance of motor.
  - Auto current down function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.
  - Be sure to adjust STOP current while motor is at standstill.
© Zero point excitation output signal (ZERO OUT)

※ The signal is output to indicate when the motor excitation status is in the initial stage. Used to check the rotation position of motor's axis.

※ In case of full step, the signal is output every 7.2°. (50 times / rotation)
EX) Full step (0.72°/Step): Signal is output every 10 pulses.
20 divisions (0.036°/Step): Signal is output every 200 pulses.

© HOLD OFF function

※ When HOLD OFF input signal is [H], motor excitation is released.
When HOLD OFF input signal is [L], motor excitation is in a normal status.
※ A function used to rotate motor's axis using external force or used for manual positioning.
※ HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.
※ Please do not use for stopping motor.

© Setting microstep (Microstep : Resolution)

<table>
<thead>
<tr>
<th>Switch No.</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
<th>9</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
<th>E</th>
<th>F</th>
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</thead>
<tbody>
<tr>
<td>Resolution</td>
<td>1</td>
<td>2</td>
<td>4</td>
<td>5</td>
<td>8</td>
<td>10</td>
<td>16</td>
<td>20</td>
<td>25</td>
<td>40</td>
<td>50</td>
<td>80</td>
<td>100</td>
<td>125</td>
<td>200</td>
<td>250</td>
</tr>
<tr>
<td>Step angle</td>
<td>0.72°</td>
<td>0.36°</td>
<td>0.18°</td>
<td>0.144°</td>
<td>0.09°</td>
<td>0.072°</td>
<td>0.045°</td>
<td>0.036°</td>
<td>0.0288°</td>
<td>0.018°</td>
<td>0.0144°</td>
<td>0.009°</td>
<td>0.0072°</td>
<td>0.00576°</td>
<td>0.0036°</td>
<td>0.00288°</td>
</tr>
</tbody>
</table>

・ Resolution setting (Same as MS1, MS2)

※ It is set to MS1 when division selection signal is [L], and MS2 when division selection signal is [H].
※ Two different micro step can be set using DIVISION SELECTION. Users can select one of them via external input signals.
※ Microstep is to make basic step angle of 5-phase motors (0.72°) divided into smaller angle according to setting values.
※ The formula for microstep angle is:

\[
\text{Motor revolution angle (5-phase motors)} = \frac{\text{Basic step angle (0.72°)}}{\text{Resolution}}
\]

※ In case of geared motors, step angle shall be determined by dividing step angle by gear ratio.
EX) 0.72° / 10 (1:10) = 0.072°
※ It may cause step-out if resolution is changed while motor is running.

© ALRAM Function

※ Over heat: When the temperature in driver BASE is over 80°C, Alarm LED will be ON and motor will stop with holding the torque. Remove the Over Heat Alarm causing factors and reset the power in order to reset alarm function.
※ Overcurrent: When overcurrent is applied to the motor due to driver damage or errors, Alarm LED will be flickering.
In case of overcurrent, the motor will be HOLD OFF. Cut off the power and remove overcurrent-causing factors in order to resume normal operation.

Input·Output diagram

※ CW
2-pulse input mode - CW direction rotation pulse input
1-pulse input mode - Operation command pulse input

※ CCW
2-pulse input mode - CCW direction rotation pulse input
1-pulse input mode - rotation direction pulse input
[H] : CW, [L] : CCW

※ HOLD OFF
Motor excitation OFF control signal
[H] : Motor excitation OFF

※ DIVISION SELECTION
Division selection signal
→ [L] : Operated by MS1 setting resolution.
[H] : Operated by MS2 setting resolution.

※ ZERO OUT
Zero point excitation output signal ON for zero point excitation
Connections

Please refer to Q-37 for standard wiring.

Dimensions

(unit: mm)

Note: Add external resistance when power for pulse from the external of the unit exceeds +5V. (Input current: 10 to 20mA).

※ Please refer to Q-37 for standard wiring.
5-Phase Micro stepper motor driver [MD5-HF14-AO]

© Function selection switch

<table>
<thead>
<tr>
<th>NO</th>
<th>Name</th>
<th>Function</th>
<th>Switch position</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>TEST</td>
<td>Self-diagnosis</td>
<td>ON / OFF</td>
</tr>
<tr>
<td>2</td>
<td>2/1 CLK</td>
<td>Pulse input method</td>
<td>1 Pulse input</td>
</tr>
<tr>
<td>3</td>
<td>C/D</td>
<td>Auto current down</td>
<td>Not using</td>
</tr>
</tbody>
</table>

- **TEST**
- Self-diagnosis function is to test motors and drivers.
- Motors rotate with 30 rpm in full-step. Motor rotation speed is subject to change depending on resolution setting.
- Rotation speed = 30 rpm / resolution
- The motor will rotate in CCW direction when in 1-pulse input mode and in CW direction when in 2-pulse input mode.
- Note) Make sure that TEST switch is set to OFF before supplying the power.
  - It may cause injury or danger if TEST switch is set to ON when power is supplied.
- **2/1 CLK**
  - 1/2 CLK switch is to select pulse input mode.
  - 1-pulse input mode: CW → operation command pulse input, CCW → rotation direction pulse input
    - ([H]: CW rotation, [L]: CCW rotation)
  - 2 Pulse input mode: CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input
- **C/D (Auto current down)**
  - This function is reducing current automatically according to STOP current setting value in order to suppress generated heat when motor is stop.
  - It activates when there is no pulse input of motor operation for over 200ms.

© RUN current setting

<table>
<thead>
<tr>
<th>Switch No.</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
<th>9</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
<th>E</th>
<th>F</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current (A/Phase)</td>
<td>0.4</td>
<td>0.5</td>
<td>0.57</td>
<td>0.63</td>
<td>0.71</td>
<td>0.77</td>
<td>0.84</td>
<td>0.9</td>
<td>0.96</td>
<td>1.02</td>
<td>1.09</td>
<td>1.15</td>
<td>1.22</td>
<td>1.27</td>
<td>1.33</td>
<td>1.4</td>
</tr>
</tbody>
</table>

- RUN current is a phase current provided to 5-phase stepper motor.
- Be sure to set RUN current at the rated current or below.
- Adjust the RUN current in case severe heat generation occurs. Be sure that torque decreasing may occur when adjusting the current.
- Note) Be sure to adjust RUN current while motor is running.

© STOP current setting

<table>
<thead>
<tr>
<th>Switch No.</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
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<th>B</th>
<th>C</th>
<th>D</th>
<th>E</th>
<th>F</th>
</tr>
</thead>
<tbody>
<tr>
<td>%</td>
<td>27</td>
<td>31</td>
<td>36</td>
<td>40</td>
<td>45</td>
<td>50</td>
<td>54</td>
<td>58</td>
<td>62</td>
<td>66</td>
<td>70</td>
<td>74</td>
<td>78</td>
<td>82</td>
<td>86</td>
<td>90</td>
</tr>
</tbody>
</table>

- STOP current is a phase current provided to 5-phase stepper motor at standstill.
- It will be activated when C/D (Auto current down) is set to ON. By setting STOP current, it is possible to suppress the heat generation at motor standstill.
- STOP current setting value is the ratio of RUN current setting value (%).
- Ex) In case RUN current setting value is set to 1.4A and STOP current setting value is set to 50%, auto current down current is set to 0.7A.
- STOP current setting value may have some deviation depending on resistance impedance of motor.
- Auto current down function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.
- Note) Be sure to adjust STOP current while motor is at standstill.
© HOLD OFF function
※When HOLD OFF input signal is [H], motor excitation is released.
When HOLD OFF input signal is [L], motor excitation is in a normal status.
※A function used to rotate motor’s axis using external force or used for manual positioning.
※HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.
※Please do not use for stopping motor.

© Setting microstep(Microstep : Resolution)

<table>
<thead>
<tr>
<th>Switch No.</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
<th>9</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
<th>E</th>
<th>F</th>
</tr>
</thead>
<tbody>
<tr>
<td>Resolution</td>
<td>1</td>
<td>2</td>
<td>4</td>
<td>5</td>
<td>8</td>
<td>10</td>
<td>16</td>
<td>20</td>
<td>25</td>
<td>40</td>
<td>50</td>
<td>80</td>
<td>100</td>
<td>125</td>
<td>200</td>
<td>250</td>
</tr>
<tr>
<td>Step angle</td>
<td>0.72°</td>
<td>0.36°</td>
<td>0.18°</td>
<td>0.09°</td>
<td>0.045°</td>
<td>0.036°</td>
<td>0.0288°</td>
<td>0.018°</td>
<td>0.0144°</td>
<td>0.009°</td>
<td>0.0072°</td>
<td>0.00576°</td>
<td>0.0036°</td>
<td>0.00288°</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

※ Resolution setting
※Microstep is to make basic step angle of 5-phase motors (0.72°) divided into smaller angle according to setting values.
※The formula for microstep angle is ;
Motor revolution angle (5-phase motors) = Basic step angle(0.72°) / Resolution

※In case of geared motors, step angle shall be determined by dividing step angle by gear ratio.
EX) 0.72° / 10 (1:10) = 0.072°
※It may cause step-out if resolution is changed while motor is running.

© ALRAM OUTPUT Function
※Overheat : When the temperature of inner driver (Base) is over 80°C, Alarm LED (Red) is turned ON and motor becomes HOLD OFF. Turn OFF the power, remove the causes, and re-supply the power to clear the alarm.
※Overcurrent : When overcurrent is applied to motor due to damage by a fire of stepper motor, broken of inner driver, or occurrence of abnormal error, Alarm LED (Red) flashes and motor becomes HOLD OFF. Turn OFF the power, remove the causes, and re-supply the power to clear the alarm.

Input-Output diagram

※CW
2-pulse input mode - CW direction rotation pulse
1-pulse input mode - Operation command pulse input

※CCW
2-pulse input mode - CCW direction rotation pulse input
1-pulse input mode - Operation command pulse
[H] : CW, [L] : CCW

※HOLD OFF
Motor excitation OFF control signal
[H] : Motor excitation OFF

※When alarm occurs, it turns HOLD OFF. After cut off the power, remove the causes to operate normally.

※Overheat

※Over current

Inner circuit of MD5-HF14-AO
### MD5 Series

#### Connections

- **Motor**
  - Blue
  - Red
  - Orange
  - Green
  - Black

- **User Controller**

  ※ Please refer to Q-37 for standard wiring.

- **Alarm out**
  - +
  - -
  - 3-SVDC

- **Motor**

  - CW+
  - CW-
  - CCW+
  - CCW-
  - HOLD OFF+
  - HOLD OFF-

**Note**
Add external resistance when power for pulse from the external of the unit exceeds +5V.
(Input current: 10 to 20mA)

- **F.G.**
  - 100-220VAC 50/60Hz

**Input current:** 10 to 20mA

### Dimensions

[unit: mm]

- 20
- 40
- 42
- 5
- 40
- 122
- 134.3
- 120
- 170
- 4-M4 TAP Dp:8
- 108
- 7
- 108
5-Phase Microstep motor driver [MD5-HF28]

© Function selection switch

<table>
<thead>
<tr>
<th>NO</th>
<th>Name</th>
<th>Function</th>
<th>Switch position</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>TEST</td>
<td>Self-diagnosis</td>
<td>ON</td>
</tr>
<tr>
<td>2</td>
<td>2/1 CLK</td>
<td>Pulse input method</td>
<td>1 Pulse input</td>
</tr>
<tr>
<td>3</td>
<td>C/D</td>
<td>Auto current down</td>
<td>Not using</td>
</tr>
</tbody>
</table>

• TEST
※Self-diagnosis function is to test motors and drivers.
※Motors rotate with 250Hz in full-step. Motor rotation speed is subject to change depending on resolution setting.
※Rotation speed = 30 rpm / resolution
※The motor will rotate in CCW direction when in 1-pulse input mode and in CW direction when in 2-pulse input mode.

Note) Make sure that TEST switch is set to OFF before supplying the power.

It may cause injury or danger if TEST switch is set to ON when power is supplied.

• 2/1 CLK
※1/2 CLK switch is to select pulse input mode.
※1-pulse input mode : CW → operation command pulse input, CCW → rotation direction pulse input
※2-pulse input mode : CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input

• C/D (Auto current down)
※This function is reducing current automatically according to STOP current setting value in order to suppress generated heat when motor is stop
※It activates when there is no pulse input of motor operation for over 200ms.

© RUN current setting

<table>
<thead>
<tr>
<th>Switch No.</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
<th>9</th>
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<th>B</th>
<th>C</th>
<th>D</th>
<th>E</th>
<th>F</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current</td>
<td>1.14</td>
<td>1.25</td>
<td>1.36</td>
<td>1.50</td>
<td>1.63</td>
<td>1.74</td>
<td>1.86</td>
<td>1.97</td>
<td>2.10</td>
<td>2.20</td>
<td>2.30</td>
<td>2.40</td>
<td>2.50</td>
<td>2.60</td>
<td>2.78</td>
<td>2.88</td>
</tr>
</tbody>
</table>

※RUN current is a phase current provided to 5-phase stepper motor.
※Be sure to set RUN current at the rated current or below.
※Adjust the RUN current in case severe heat generation occurs. Be sure that torque decreasing may occur when adjusting the current.

Note) Be sure to adjust RUN current while motor is running.

© STOP current setting

<table>
<thead>
<tr>
<th>Switch No.</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
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<tr>
<td>%</td>
<td>27</td>
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<td>36</td>
<td>40</td>
<td>45</td>
<td>50</td>
<td>54</td>
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<td>66</td>
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<td>74</td>
<td>78</td>
<td>82</td>
<td>86</td>
<td>90</td>
</tr>
</tbody>
</table>

※STOP current is a phase current provided to 5-phase stepper motor at standstill.
※It will be activated when C/D (Auto current down) is set to ON. By setting STOP current, it is possible to suppress the heat generation at motor standstill.
※STOP current setting value is the ratio of RUN current setting value (%).
※Ex) In case RUN current setting value is set to 1.4A and STOP current setting value is set to 50%, auto current down current is set to 0.7A.
※STOP current setting value may have some deviation depending on resistance impedance of motor.
※Auto current down function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.

Note) Be sure to adjust STOP current while motor is at standstill.
© Zero point excitation output signal (ZERO OUT)

※ The signal is output to indicate when the motor excitation status is in the initial stage. / Used to check the rotation position of motor's axis
※ In case of full step, the signal is output every 7.2°. (50 times / rotation)
EX) Full step (0.72°/Step) : Signal is output every 10 pulses.
20 divisions (0.036°/Step) : Signal is output every 200 pulses.

© HOLD OFF function
※ When HOLD OFF input signal is [H], motor excitation is released.
When HOLD OFF input signal is [L], motor excitation is in a normal status.
※ A function used to rotate motor's axis using external force or used for manual positioning.
※ HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.
※ Please do not use for stopping motor.

© Setting microstep(Microstep : Resolution)

※ It is set to MS1 when division selection signal is [L], and MS2 when division selection signal is [H].
※ Two different micro step can be set using DIVISION SELECTION. Users can select one of them via external input signals.
※ Microstep is to make basic step angle of 5-phase motors (0.72°) divided into smaller angle according to setting values.
※ The formula for microstep angle is;
Motor revolution angle (5-phase motors) = Basic step angle(0.72°) / Resolution
※ In case of geared motors, step angle shall be determined by dividing step angle by gear ratio.
EX) 0.72° / 10 (1:10) = 0.072°
※ It may cause step-out if resolution is changed while motor is running.

© ALRAM Function
※ Over heat : When the temperature in driver BASE is over 80°C, Alarm LED will be ON and motor will stop with holding the torque. Remove the Over Heat Alarm causing factors and reset the power in order to reset alarm function.
※ Overcurrent : When overcurrent is applied to the motor due to driver damage or errors, Alarm LED will be flickering. In case of overcurrent, the motor will be HOLD OFF. Cut off the power and remove overcurrent-causing factors in order to resume normal operation.

Input-Output diagram
Stepper Motor Driver (2.8A/phase, AC Power)

**Connections**

- Photo electric sensor
- Fiber optic sensor
- Door/Area sensor
- Proximity sensor
- Pressure sensor
- Rotary encoder
- Connector/Socket
- Temp. controller
- SSR/Power controller
- Counter
- Timer
- Panel meter
- Tacho/Speed/Pulse meter
- Display unit
- Sensor controller
- Switching mode power supply
- Stepper motor & Driver & Controller
- Graphic/Logic panel
- Field network device
- Software
- Other

**Note:** Add external resistance when power for pulse from the external of the unit exceeds +5V.
(Input current: 10 to 20mA)

※ Please refer to Q-37 for standard wiring.

**Dimensions** (unit: mm)

<table>
<thead>
<tr>
<th>Width</th>
<th>Height</th>
<th>Depth</th>
<th>Dimensions</th>
</tr>
</thead>
<tbody>
<tr>
<td>146mm</td>
<td>54.1mm</td>
<td>146mm</td>
<td></td>
</tr>
<tr>
<td>185mm</td>
<td>176mm</td>
<td>163mm</td>
<td></td>
</tr>
<tr>
<td>49mm</td>
<td>20mm</td>
<td>5mm</td>
<td></td>
</tr>
</tbody>
</table>

*(Input current: 10 to 20mA)*

Note: Add external resistance when power for pulse from the external of the unit exceeds +5V.

*Input current: 10 to 20mA*
**Function selection switch**

<table>
<thead>
<tr>
<th>NO</th>
<th>Name</th>
<th>Function</th>
<th>Switch position</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1/2 CLK</td>
<td>Pulse input method</td>
<td>ON</td>
</tr>
<tr>
<td>2</td>
<td>FULL ↔ HALF</td>
<td>Resolution Setting</td>
<td>0.72° 0.36°</td>
</tr>
</tbody>
</table>

- **1/2 CLK**
  - 1/2 CLK switch is to select pulse input mode.
  - 1-pulse input mode: CW → operation command pulse input, CCW → rotation direction pulse input (H: CW rotation, L: CCW rotation)
  - 2 Pulse input mode: CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input

- **FULL ↔ HALF**
  - FULL ↔ HALF switch is to select pulse input mode.
  - If changing resolution while the motor is running, it may cause step-out.

**RUN current setting**

- RUN current is a phase current provided to 5-phase stepper motor.
- Be sure to set RUN current at the rated current or below.
- RUN current setting range: 0.5 to 1.5A
- When changing RUN current, connect CP+ to voltmeter (+) terminal and CP- to voltmeter (-) terminal, then adjust the volume.
- The formula for phase-current setting is:
  \[ \text{Setting current (A)} = \frac{\text{CP Input Voltage (V)}}{2} \]
- Adjust the RUN current in case severe heat generation occurs. Be sure that torque decreasing may occur when adjusting the current.
  Note) Be sure to adjust RUN current while motor is running.

**STOP current setting**

- STOP current is a phase current provided to 5-phase stepper motor at standstill.
- A function to reduce the current in order to suppress the heat generation at motor standstill / STOP current setting range: 25 to 75% of RUN current using VR
- In case Run current setting value is set to 1.0A and STOP current setting value is set to 50%, STOP current is set to 0.5A.
- STOP current setting value may have some deviation depending on resistance impedance of motor.
- STOP current function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.
- STOP current function will be activated when no operation command pulse is input within 500ms.
  Note) Be sure to adjust STOP current while motor is at standstill.

**HOLD OFF function**

- When HOLD OFF input signal is [H], motor excitation is released.
  When HOLD OFF input signal is [L], motor excitation is in a normal status.
- A function used to rotate motor's axis using external force or used for manual positioning.
- HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.
- Please do not use for stopping motor.
Stepper Motor Driver (1.5A/phase, AC Power)

Input diagram

- CW
  2 pulse input method (CW direction rotation pulse input)
  1 pulse input method (Operating command pulse input)
  Note: If the power for driving pulse from external is over than +5V, please connect resistor

- CCW
  2 pulse input method (CCW direction rotation pulse input)
  1 pulse input method (Rotating direction pulse input)
  → [H] : CW, [L] : CCW

- HOLD OFF
  The control signal for hold off of Motor → [H] : Motor Hold Off

Connections

- Add external resistance when power for pulse from the external of the unit exceeds +5V.
  (Input current: 10 to 20mA)

- Please refer to Q-37 for standard wiring.

Dimensions

(unit: mm)

Note: CW
- CW+ and CW- are for pulse input method (CW direction rotation pulse input).
- CCW+ and CCW- are for pulse input method (CCW direction rotation pulse input).
- HOLD OFF+ and HOLD OFF- are for HOLD OFF (The control signal for hold off of Motor).

Note: CCW
- CW+ and CW- are for pulse input method (CW direction rotation pulse input).
- CCW+ and CCW- are for pulse input method (CCW direction rotation pulse input).
- HOLD OFF+ and HOLD OFF- are for HOLD OFF (The control signal for hold off of Motor).

Note: HOLD OFF
- The control signal for hold off of Motor → [H] : Motor Hold Off

Specifications:
- Stepper Motor Driver (1.5A/phase, AC Power)