



# SR1 Series

## ■ Specifications

### ○ Input

		4-30VDC input voltage	90-240VAC input voltage
Input voltage range		4-32VDC	85-264VACrms(50/60Hz)
Max. input current		9mA(Zero cross turn-on), 13mA(Random turn-on)	7mArms(240VACrms)
Pick-up voltage		4VDC	85VACrms
Drop-out voltage		1VDC	10VACrms
Turn-on time	Zero cross turn-on	Max. 0.5 cycle of load source + 1ms	
	Random turn-on	Max. 1ms	
Turn-off time		Max. 0.5 cycle of load source + 1ms	Max. 1.5 cycle of load source + 1ms

### ○ Output

		24-240VAC load voltage					48-480VAC load voltage				
Load voltage range(50/60Hz)		24-264VACrms(50/60Hz)					48-528VACrms(50/60Hz)				
Rated load current Ta=25°C	Resistive load (AC-51)	15Arms	25Arms	40Arms	50Arms	75Arms	15Arms	25Arms	40Arms	50Arms	75Arms
	Motor load (AC-53a)	—					5Arms	8Arms		15Arms	
Min. load current		0.15Arms	0.2Arms		0.5Arms		0.5Arms				
Max. 1cycle surge current (60Hz)		190A	270A	330A	1000A		300A	500A		1000A	
Max. non-repetitive surgecurrent(I <sup>2</sup> t, t=8.3ms)		150A <sup>2</sup> S	300A <sup>2</sup> S	500A <sup>2</sup> S	4000A <sup>2</sup> S		350A <sup>2</sup> S	1000A <sup>2</sup> S		4000A <sup>2</sup> S	
Peak voltage(non-repetitive)		600V					1200V(zero cross turn-on), 1000V(random turn-on)				
Leakage current(Ta=25°C)		Max. 10mArms									
Output on voltage drop[Vpk] (Max. load current)		Max. 1.6V									
Static off-state dv/dt		500V/μs									

※ For controlling motor load, use the product which load voltage range is within 48-480VACrms.

### ○ General Specifications

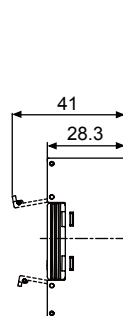
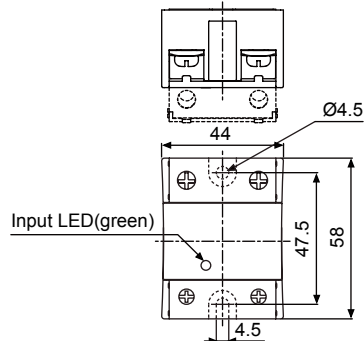
Certification	UL508, CSA22.2 No.14 and IEC/EN 60947-4-3	
Dielectric strength(Vrms)	4000VAC 50/60Hz 1min.(input-output, input/output-case)	
Insulation resistance	Min. 100MΩ(at 500VDC megger)	
Input LED	Green	
Environment	Ambient temperature	-30 to 80°C, storage: -30 to 100°C(Rated load current capacity is different based on the surrounding temperature. Refer to '■ SSR Derating curve'.)
	Ambient humidity	45 to 85%RH, storage: 45 to 85%RH
Input terminal connection	Min. 1×0.5mm <sup>2</sup> (1×AWG20) Max. 1×1.5mm <sup>2</sup> (1×AWG16) or 2×1.5mm <sup>2</sup> (2×AWG16)	
Output terminal connection	Min. 1×1.5mm <sup>2</sup> (1×AWG16) Max. 1×16mm <sup>2</sup> (1×AWG6) or 2×6mm <sup>2</sup> (2×AWG10)	
Input terminal fixed torque	0.75 to 0.95N·m	
Output terminal fixed torque	1.6 to 2.2N·m	
Unit weight	Approx. 73g	

※ For wiring the terminal, an O-ring terminal must be used.

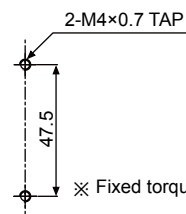
※ Environment resistance is rated at no freezing or condensation.

## ■ Dimensions

(unit: mm)



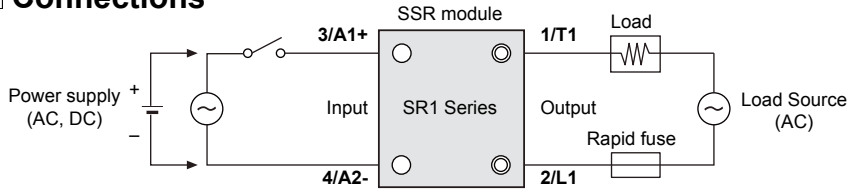
### ○ Hole cut-out for panel front mounting



※ Fixed torque : 1.8 to 2.5N·m

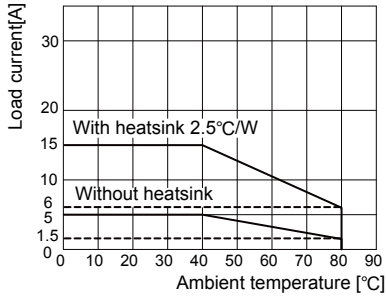
# Heatsink separated Type SSR

## Connections

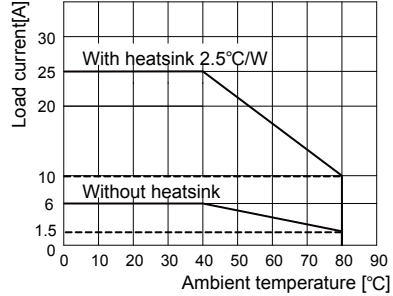


## SSR Characteristic curve

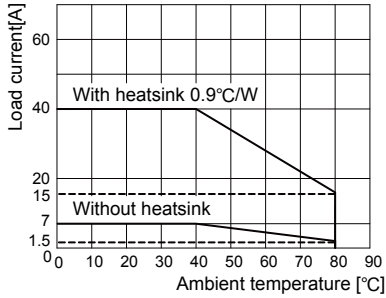
### SR1-1215/4215



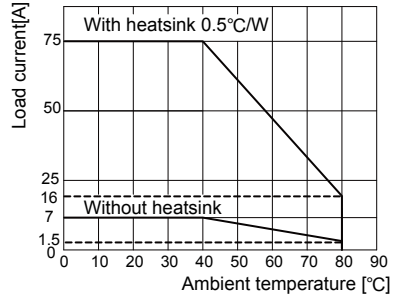
### SR1-1225/4225



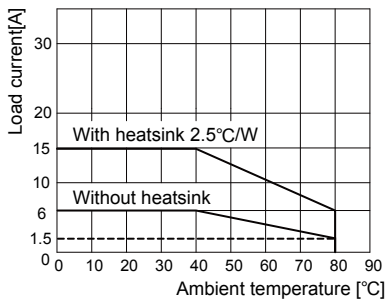
### SR1-1240/4240



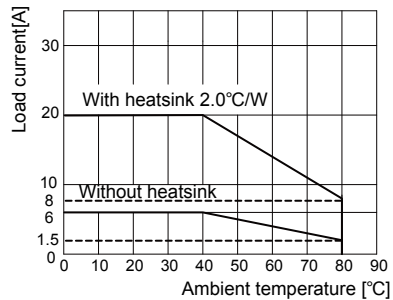
### SR1-1275/1475/1475R/4275/4475



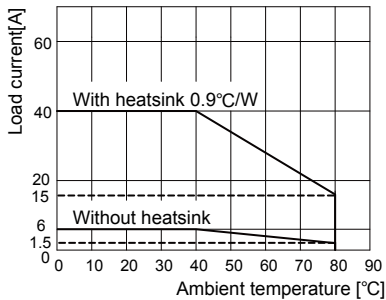
### SR1-1415/1415R/4415



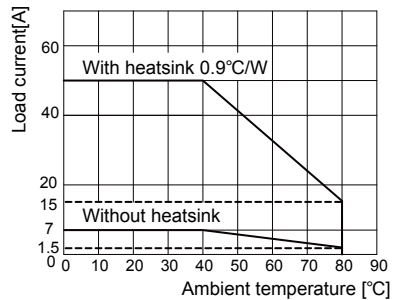
### SR1-1425/1425R/4425



### SR1-1440/1440R/4440



### SR1-1250/1450/1450R/4250/4450



(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/Socket

(H) Temp. controller

(I) SSR/Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/Speed/Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching mode power supply

(Q) Stepper motor & Driver/Controller

(R) Graphic/Logic panel

(S) Field network device

(T) Software

(U) Other

## ■ Proper usage



### High temperature caution

**Make sure do not touch the heat sink or the unit body while power is supplied or right after load power is turned off. If not, it may cause a burn.**



### Caution for using

1. Attach a heatsink and ventilate for smooth convection current. If not, congested heat transfer may cause product failure or malfunction.
2. For mounting multiple SSR, please keep certain installation intervals for heat prevention. For horizontal installation (when the heights of input part and output part are equal), it is recommended to apply less than 50% of the rated load current.
3. Make sure do not touch the heatsink or the unit body while power is supplied or right after load power is turned OFF. If not, it may cause a burn.
4. Connect the proper cable for the rated load current with output terminal.
5. Use rapid fuse of which  $I^2t$  is under 1/2 of SSR  $I^2t$  in order to protect the unit from load's short-circuit current.
6. In case of a short-circuit please replace the fuse with a 1/2 of SSR  $I^2t$  value specified semiconductor protective type.
7. In case that load's current is lower than SSR min. load current, connect dummy resistance to the load in parallel so as to make load's current higher than SSR min. load current.
8. When selecting phase control with random turn-on model, install the noise filter between load and load's source.
9. Make sure that the screw on output terminal is tightly fastened. Using the unit with loose bolt may cause product failure or malfunction.
10. Do not touch the load's terminal even if output is OFF. It may cause electric shock.
11. The signal input of the 4-30VDC model should be supplied by the insulated and limited voltage/current or by Class 2 power supply.
12. To attach the heatsink, use Thermal Grease as below or that of equal specification.  
× Thermal Grease: GE TOSHIBA(YG6111), KANTO-KASEI(FLOIL G-600), SHINETSU(G746)
13. Proper application environment (Avoid following environments to install)
  - ① Where temperature/humidity is beyond the specification
  - ② Where dew condensation occurs due to temperature change
  - ③ Where inflammable or corrosive gas exists
  - ④ Where direct rays of light exist
  - ⑤ Where severe shock, vibration or dust exists
  - ⑥ Where near facilities generating strong magnetic forces or electric noise
14. Installation environment
  - ① It shall be used indoor
  - ② Altitude Max. 2,000m
  - ③ Pollution Degree 2
  - ④ Installation Category III