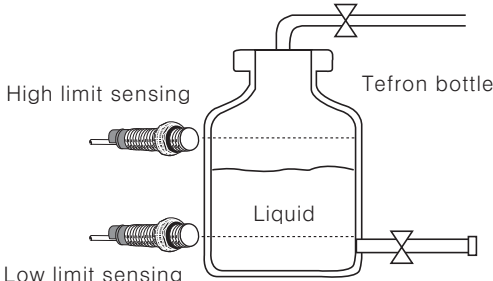
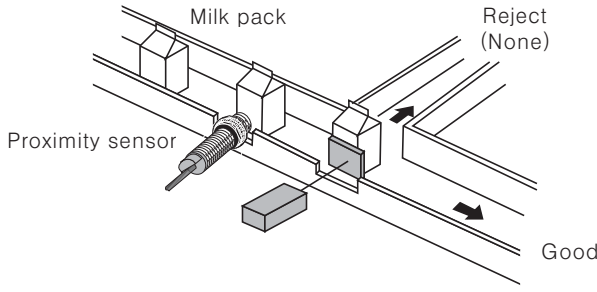
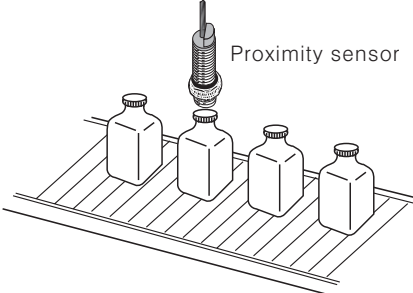
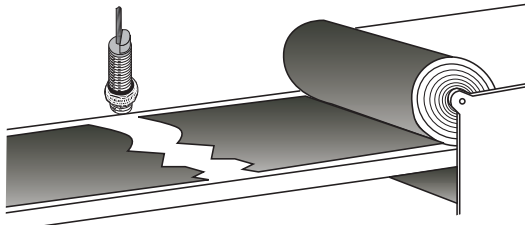
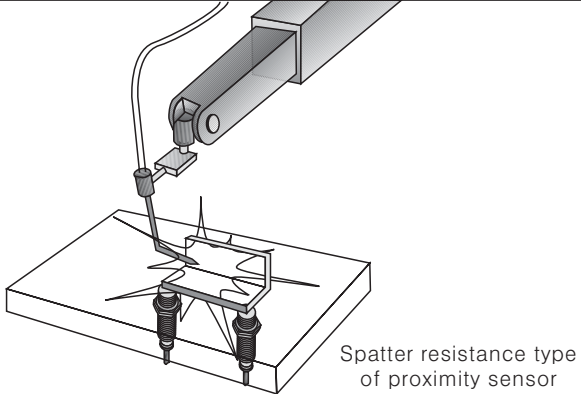
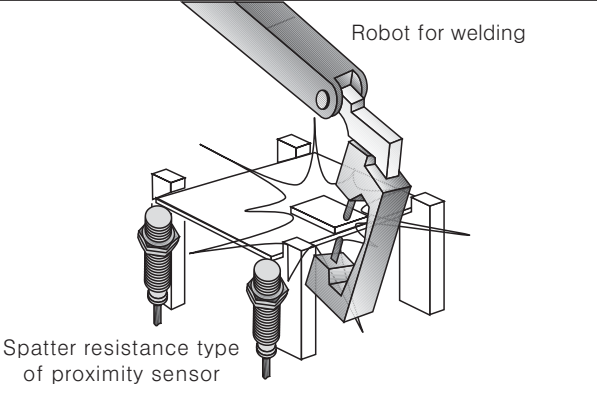
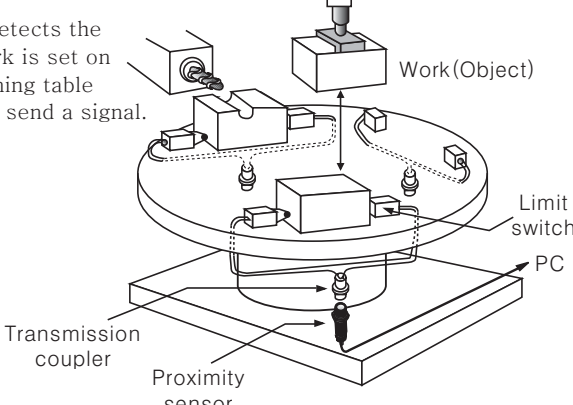
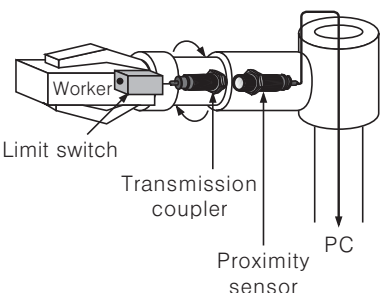
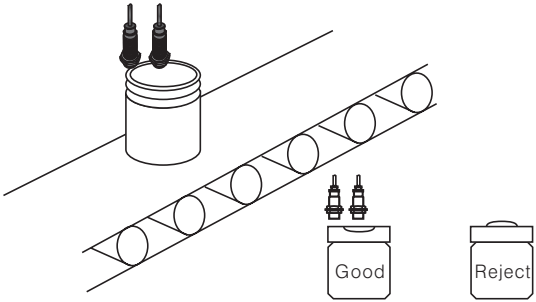
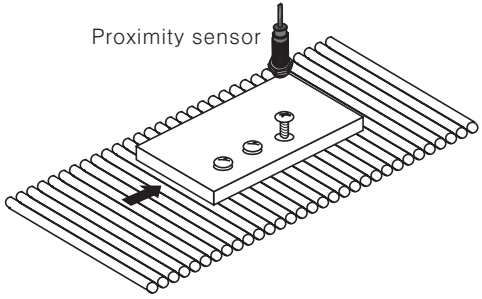
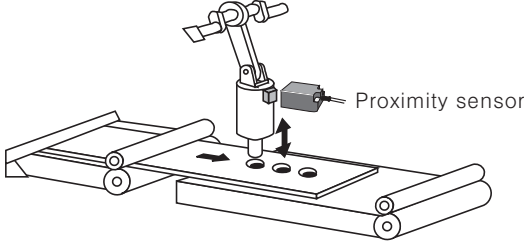
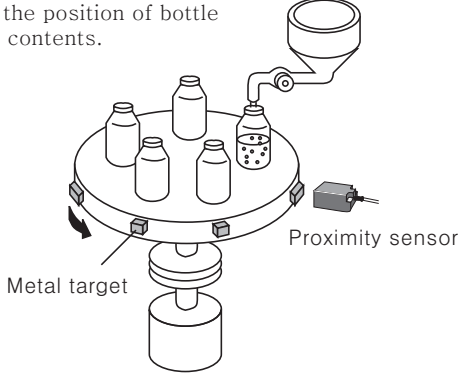
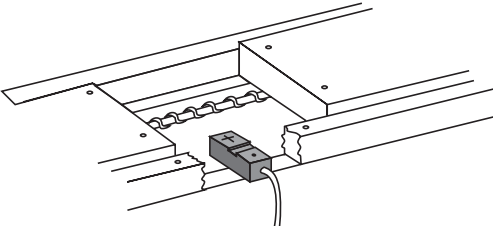
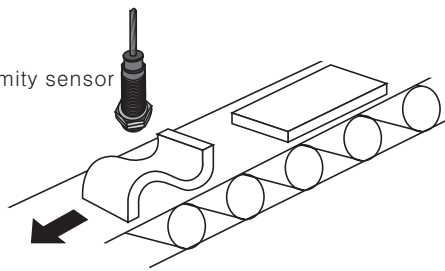
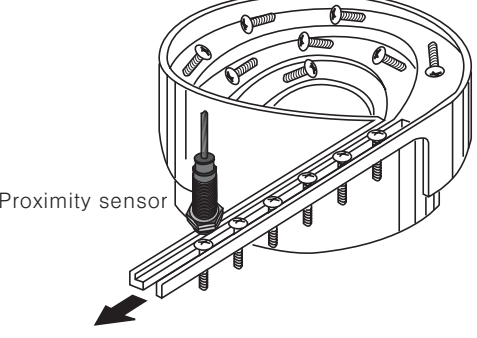
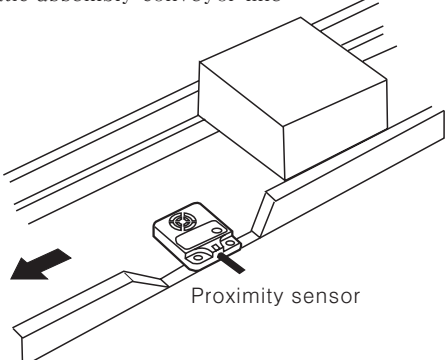


■ Applications

| | | |
|--|---|---|
| <p>Detection of liquid level(Capacitive type)</p> <p>It is able to detect the level of liquid inside of bottle from outside.</p>  <p>High limit sensing</p> <p>Tefron bottle</p> <p>Liquid</p> <p>Low limit sensing</p> | <p>Detecting Milk in paper pack(Capacitive type)</p> <p>It is able to detect milk in side of pack by capacitive proximity sensor.</p>  <p>Milk pack</p> <p>Reject (None)</p> <p>Proximity sensor</p> <p>Good</p> | (A) Counter |
| <p>Detection of cap of bottles(Capacitive)</p>  <p>Proximity sensor</p> | <p>Detection of band detectives(Capacitive)</p>  <p>Proximity sensor</p> | (B) Timer |
| <p>Fixing the point to be welded(Arc)</p>  <p>Spatter resistance type of proximity sensor</p> | <p>Checking the position for Spot welding</p>  <p>Robot for welding</p> <p>Spatter resistance type of proximity sensor</p> | (C) Temp. controller |
| <p>Turning table(Transmission coupler)</p> <p>It detects the work is set on turning table and send a signal.</p>  <p>Work(Object)</p> <p>Limit switch</p> <p>PC</p> <p>Transmission coupler</p> <p>Proximity sensor</p> | <p>Transmitting the signal of checking(Transmission coupler)</p> <p>It detects if the robot arm is holding the work and send a signal.</p>  <p>Worker</p> <p>Limit switch</p> <p>Transmission coupler</p> <p>Proximity sensor</p> <p>PC</p> | (D) Power controller |
| | | (E) Panel meter |
| | | (F) Tacho/ Speed/ Pulse meter |
| | | (G) Display unit |
| | | (H) Sensor controller |
| | | (I) Switching power supply |
| | | (J) Proximity sensor |
| | | (K) Photo electric sensor |
| | | (L) Pressure sensor |
| | | (M) Rotary encoder |
| | | (N) Stepping motor & Driver & Controller |
| | | (O) Graphic panel |
| | | (P) Production stoppage models & replacement |

Applications

■ Applications

| | |
|--|---|
| <p>Detecting condition of cans</p> <p>Proximity sensor</p>  | <p>Measuring the height of screw</p> <p>Detecting the status of screw</p> <p>Proximity sensor</p>  |
| <p>Controlling a press</p> <p>Making a hole on panel by constant distance</p>  <p>Proximity sensor</p> | <p>Positioning control</p> <p>Detecting the position of bottle for fill the contents.</p>  <p>Proximity sensor</p> <p>Metal target</p> |
| <p>Detecting position of target</p> <p>Automatic assembly conveyor line</p>  <p>Proximity sensor</p> | <p>Sensing incorrect shape of target</p>  <p>Proximity sensor</p> |
| <p>Counting screws</p>  <p>Proximity sensor</p> | <p>Detecting position of target(PFI 25)</p> <p>Automatic assembly conveyor line</p>  <p>Proximity sensor</p> |